Lecture #4: Stochastic bandits (Part)

Explore-then-Commit

(input NEIN)

Pull each arm N times.

Let $k^{\bullet} \in \operatorname{argmax} \hat{\mu}_{k}(Nk)$

Play & until time T

Simple algorithm clearly separating exploration from exploitation.

Easy analysis

Theorem ETC with N= ln T satisfies

 $R_{T} \leqslant \sum_{\substack{a=1 \ Da0}}^{R} \Delta_{a} \ln T + \Delta_{R}$

Proof: Similarly to Greedy in the full info petting:

For n=1, N let ta(n) be the deterministic time where k is pulled for the n-th time.

By Hoefding megnality

 $\mathbb{P}\left(\frac{1}{N}\sum_{n=1}^{N}X_{\mathbf{g}}\left(h_{\mathbf{g}(n)}-X_{\mathbf{g}(n)}\left(h_{\mathbf{g}(n)}\right)\right)<\mathbf{e}^{-N\sum_{n=1}^{N}X_{\mathbf{g}}\left(h_{\mathbf{g}(n)}-X_{\mathbf{g}(n)}\left(h_{\mathbf{g}(n)}\right)\right)}$

So: $R_{+} < \sum_{k=1}^{K} N \Delta_{k} + \sum_{k=1}^{K} \Delta_{k} (T-N) e^{-N \Delta_{k}}$ Plugging the value of N: $R_{T} \leqslant \sum_{\alpha=1}^{K} \frac{\Delta_{\alpha}}{\Delta^{\alpha}} \ln T + \Delta_{\alpha}$ Remark: Again we can get a distribution-free bound realing as O((K lyT) 1/3 T 2/3), and the motiona dependent vision requires knowledge of O Two main drawbachs of these methods:

. they require browledge of D. • they scale in $\frac{1}{5^2}$ (n $T^{2/3}$ in distribution-fee bounds) This is because they use a uniform exploration: each arm is explored the same amount of time.

exploration rounds depend
on past observations. A better strategy is to use an adaptive exploration: better aims are explored more often. Theiden is that a very bad arm is quicker to detect as seeb-optimal.

Successive Eliminations

Let K=[K]

While God (X)>1:

Pull each own in Konce

For RGK:

if $\hat{\mu}_{k}(t) + \sqrt{\frac{2\ell_{n}T}{N_{k}(t)}} \ll \frac{\hat{\mu}_{k}(t)}{\hat{\mu}_{k}(t)} - \sqrt{\frac{2\ell_{n}T}{N_{k}(t)}}$ Then $\mathcal{K} \leftarrow \mathcal{K} \setminus \{k\}$

Pull the orly am in K until the end

Theren: For SE, the regul salisfies for any TEN:

$$R_{T} \leq \sum_{k,\Delta_{R},o} \left(\frac{32\ln T}{\Delta_{k}} + 1\right) + \frac{K}{T}$$

Proof: Define the clean event

$$\mathcal{E} = \left\{ \begin{array}{c} \forall k \neq k^*, \forall r \in [T], & \hat{\mu}_{\alpha}(r) - \mu_{\alpha} < \sqrt{\frac{2 \cdot (nT)}{N \cdot (r)}} \\ \forall r \in [T], & \hat{\mu}_{\alpha^*}(r) - \mu_{\alpha^*} > - \sqrt{\frac{2 \cdot (nT)}{N_{\alpha^*}(r)}} \end{array} \right\}$$

Thanks to our concentration lemma on pia:

We now bound EINe(T) 1/[E]].

Note that when E holds, we always have:

Mac (+)+ (Zent > Mac > Ma (+) - (Zent Na (+))

So be is never eliminated from K.

For a suboptimilaring, let No be the smallest integer such that

4 \ \ \frac{z ln T}{N_R(F)} \ \ \Da

 $V_{k} = \sqrt{\frac{32ln}{\Delta_{k}^{2}}}$

Then once all arms in X have been pulled Na times, we have if Eholds

So be is eliminated after at most Ne pulls if E holds;

[Ne(t) 1] < Baz

$$\left\langle \begin{array}{c} Z & \Delta_{k} & \overline{32lnT} \\ \ell_{k}\Delta_{k} & \overline{\Delta_{k}^{2}} \end{array} \right\rangle + T(1-P(\epsilon))$$

$$<\frac{2}{6}\left(32\frac{\ln T}{\Delta_R}+1\right)$$
 + $\frac{K}{T}$

Remarks SE assumes a prior browledge of T assuming T is not too restrictive in practice, as we can use the doubling Mich see exercise session #2

- · we can easily get a better constant than 32
- This instance dependent bound also implies a distribution free bound O(JTKenT') see exercise session #2.

Upper Confidence Bound (UCB)

Pull each arm once

· tready, Sent with UCB ocores

no underestimation of py (with high presolity).

No prior knowledge of T.

Theorem

For any TEIN, the regret of UCB sotiofies $R_{T} \left\langle \sum_{k_{i} \Delta a > 0} \left\{ \frac{8 \ln T}{\Delta a} + 2 \right\} \right.$

For 13 K+1 and hth, lit

$$\mathcal{E}_{R,F} = \left\{ \begin{array}{c} \hat{\mu}_{\alpha}(r) - \mu_{\alpha} \times \sqrt{\frac{2 \ln F}{N_{\alpha}(r)}} \\ \hat{\mu}_{\alpha}(r) - \mu_{\alpha} > \sqrt{\frac{2 \ln F}{N_{\alpha}(r)}} \end{array} \right\}$$

If Exp holds and R + R is pulled at time to then;

In particular,

Mr.
$$t2\sqrt{\frac{2\ln t}{N_{R}(t_{1})}} \ge \mu k$$

To $\left(\xi_{R} \text{ and } q_{r} \cdot k\right) \Longrightarrow N_{R}(t_{1}) \le \frac{8\ln t}{\Delta_{R}^{2}}$

From here for $k \neq k^{2}$

$$\mathbb{E}\left[N_{R}(T)\right] = 1 + \mathbb{E}\left[\sum_{t \in K+1} \mathbb{I}\left(a_{r} \cdot k \text{ and } C_{R}\right) + 1\left(a_{r} \cdot k \text{ and } n_{r}t(c_{R})\right)\right]$$

$$\le 1 + \mathbb{E}\left[\sum_{t \in K+1} \mathbb{I}\left(a_{r} \cdot k \text{ and } N_{R}(t_{1}) \cdot \frac{8\ln t}{\Delta_{R}}\right) + 2\sum_{t \in K+1} \frac{1}{t^{2}} \cdot \frac{1}{t^{2}}\right]$$

$$\le 1 + \mathbb{E}\left[\sum_{t \in K+1} \mathbb{I}\left(a_{r} \cdot k \text{ and } N_{R}(t_{1}) \cdot \frac{8\ln t}{\Delta_{R}}\right) + 2\int_{0.5}^{\infty} ds$$

$$\langle 1+ \left(\frac{8hT}{\Delta^2}\right) + 1 - 1 + \left(\frac{1}{2}\right)^2$$

$$<2+\frac{8\ln T}{\Delta_{\ell}}$$

The 85 Ent motorice dependent bound in nearly aptimal. We'll see in exercise session that UCB can be made applicated with respect to the lower bound we are going to prove next week.

Principle: aiming at the best statistically possible scenario is a good strategy here.

. Previous algorithms/neoults hold for independent bounded rewards

Xe (1) ∈ [0,1]

They can be easily extended to independent or sub-gaussian rewards, as similar concentration bounds hold.

eg VCB ocones become

What if Junknown? can be estimated see exercise session #3.